ILLINOIS VALLEY COMMUNITY COLLEGE

COURSE OUTLINE

DIVISION: Workforce Development Division

COURSE: ELE 1205; Programmable Logic Controllers II

Date:	Summer	2014		
Credit Hours:		3.0		
Prerequisite(s):		ELE 1204		
Delivery Me	ethod:	 Lecture Seminar Lab Clinical Online Blended 	2 0 2 0	Contact Hours (1 contact = 1 credit hour) Contact Hours (1 contact = 1 credit hour) Contact Hours (2 contact = 1 credit hour) Contact Hours (3 contact = 1 credit hour)
Offered:	Fall	🖂 Spring	🗌 Sumn	ner

IAI Equivalent - Only for Transfer Courses-go to http://www.itransfer.org:

CATALOG DESCRIPTION:

This course is a continuation of ELE 1204, emphasizing PLC systems, advanced programming, networking, and troubleshooting.

GE	GENERAL EDUCATION GOALS ADDRESSED													
[See the last page of this form for more information.] Upon completion of the course, the student will be able: [Choose those goals that apply to this course.]														
	 Io apply analytical and problem solving skills to personal, social and professional issues and situations. To communicate orally and in writing, socially and interpersonally. To develop an awareness of the contributions made to civilization by the diverse cultures of the world. To understand and use contemporary technology effectively and to understand its impact on the individual and society. To work and study effectively both individually and in collaboration with others. To understand what it means to act ethically and responsibly as an individual in one's career and as a member of society. To develop and maintain a healthy lifestyle physically, mentally, and spiritually. To appreciate the ongoing values of learning, self-improvement, and career planning. 													
EX Up Wit 1.	 EXPECTED LEARNING OUTCOMES AND RELATED COMPETENCIES: [Outcomes related to course specific goals.] Upon completion of the course, the student will be able to: With the use of reference materials and with 70% accuracy, the student will be able to: 1. Explain Programmable Controller uses, advantages, and components. Competency 1.1. State why use PLC's at all. Competency 1.2. Explain advantages to using. Competency 1.3. Calculate monetary advantages to PLC use over Relay Logic. Competency 1.4. Correctly Identify and state uses for each component of a PLC system. Competency 1.5. Initialize a PLC. 													
2.	Program a Controll Competency 2.1. Competency 2.2. Competency 2.3. Competency 2.4.	er to operate different systems. Program a start stop jog. Program using a counter and comparators. Program a PLC timer application. Program a system to convert between decimal, octal, hex, binary and BCD numbers.												
3.	Utilize a Sequence Competency 3.1. Competency 3.2. Competency 3.3. Competency 3.4. Competency 3.5.	r program. Explain SQI, SQO and SQC instructions. State uses for each sequencer. Correctly use SQO instruction in a lab setting. Demonstrate the SQO to load timers and outputs in the same program. Network to another PLC.												

4. Properly use HMI Programming Terminals. Competency 4.1. Define HMI terminals. Competency 4.2. Connect HMI devices To the PLC. Competency 4.3. Program HMI terminal for a PLC system.

- 5. Troubleshoot for a PLC system.
 - Competency 5.1. Write prints for a PLC job.
 - Competency 5.2. Choose the correct wiring for the system.
 - Competency 5.3. Troubleshoot some common problems.
 - Competency 5.4. Develop a maintenance checklist.
 - Competency 5.5. Correctly enter and run/edit a program.
- 6. Automate a process.
 - Competency 6.1. Correctly state in writing the process to be automated.
 - Competency 6.2. Correctly use symbols to develop a wiring diagram.
 - Competency 6.3. Write a documented program to perform the process.

Competency 6.4. Write a user manual for the process.

COURSE TOPICS AND CONTENT REQUIREMENTS:

- I. Programmable Logic Controllers (PLCs): An Overview
- II. Basics of PLC Programming
- III. Developing PLC Programs From a Sequence of Operations
- IV. Program Timers
- V. Program Counters
- VI. Program Control Instructions
- VII. Data Manipulation Instructions
- VIII. Math Instructions
- IX. Sequencer Instructions
- X. PLC Communications/Networking
- XI. HMI Programming
- XII. PLC Troubleshooting Techniques

INSTRUCTIONAL METHODS:

- Laboratory work
- Demonstrations
- Lecture Discussion
- Reading assignments
- Homework
- Quizzes

INSTRUCTIONAL MATERIALS:

- 1. The student must meet the objectives of the course stated previously.
- 2. Laboratory reports must be completed as directed and receive an evaluation for accuracy of 70% or more using criteria set forth in the laboratory directions.
- 3. Grade for the course will be based upon the following:

Laboratory work	50%
Written tests and quizzes	30%
In Class Feedback	10%
Homework assignments	10%

STUDENT REQUIREMENTS AND METHODS OF EVALUATION:

Programmable Logic Controls, Gates.

OTHER REFERENCES

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Course Competency/Assessment Methods Matrix

ELE 1205; Programmable Logic Controllers II											A	lss	ses	sn	ner	nt C	Dpt	tio	ns													
For each competency/outcome place an "X" below the method of assessment to be used.	Assessment of Student Learning	Article Review	Case Studies	Group Projects	Lab Work	Oral Presentations	Pre-Post Tests	Quizzes	Written Exams	Artifact Self Reflection of Growth	Capstone Projects	Comprehensive Written Exit Exam	Course Embedded Questions	Multi-Media Projects	Observation	Writing Samples	Portfolio Evaluation	Real World Projects	Reflective Journals	Applied Application (skills) Test	Oral Exit Interviews	Accreditation Reviews/Reports	Advisory Council Feedback	Employer Surveys	Graduate Surveys	Internship/Practicum /Site Supervisor Evaluation	Licensing Exam	In Class Feedback	Simulation	Interview	Written Report	Assignment
Assessment Measures – Are direct or indirect as indicated. List competencies/outcomes below.	Direct/ Indirect	۵	۵	۵	D	D	D	D	D	Δ	D	Δ	D	D	D	D	D	D	D	D					D	D						
1.1 State why use PLC's at all.					Х		Х	Х	Х																			Х				
1.2 Explain advantages to using.					х		Х	Х	Х																			Х				
1.3 Calculate monetary advantages to PLC use over Relay Logic.					x		x	x	х																			x				
1.4 Correctly Identify and state uses for each component of a PLC system.					x		x	Х	х																			x				
1.5 Initialize a PLC.					х		Х	Х	Х																			Х				
2.1 Program a start stop jog.				х	х			Х							Х													х	х			Х
2.2 Program using a counter and comparators.				x	x			х							х													x	x			x
2.3 Program a PLC timer application.				х	х			Х							Х													х	х			Х
2.4 Program a system to convert between decimal, octal, hex, binary and BCD numbers.				x	x			x							x													x	x			x
3.1 Explain SQI, SQO and SQC instructions.				x	х			x	х						х													x	x			x
3.2 State uses for each sequencer.				Х	Х			Х	Х						Х													Х	х			Х
3.3 Correctly use SQO instruction in a lab setting.				x	x			x	x						x													x	x			х

Curriculum Committee – Course Outline Form Revised 02/2/10

3.4 Demonstrate the SQO to load timers		x			y	x			x							x	X		x
and outputs in the same program.		^ _ ^	`		^	^			^							^	^		^
3.5 Network to another PLC.		x	<		Х	х			x							х	Х		Х
4.3 Define HMI terminals.		x	$\langle \rangle$	(x							Х	Х		Х
4.2 Connect HMI devices To the PLC.		x >	$\langle \rangle$	(х							Х	Х		Х
4.1 Program HMI terminal for a PLC				,					v							X	v		v
system.		×	$\left(\right)$						X							X	X		X
5.1 Write prints for a PLC job.		x >	۲			Х			Х							Х	Х	i	Х
5.2 Choose the correct wiring for the			,			v			v							v	v	i	v
system.		×				X			X							X	X		X
5.3 Troubleshoot some common			,			×			v							X	v		v
problems.		~ /				×			^							X	X		X
5.4 Develop a maintenance checklist.		x >	<			Х			х							Х	Х		Х
5.5 Correctly enter and run/edit a			,			×			v							X	v		v
program.		x				X			X							X	X		X
6.1 Correctly state in writing the process				,			v		v										v
to be automated.		x		(X		X										X
6.2 Correctly use symbols to develop a				,			v		v									i	v
wiring diagram.		x		(X		X										X
6.3 Write a documented program to				,			v		v										v
perform the process.		\sim					X		×										X
6.4 Write a user manual for the process.		x >	$\langle \rangle$	<			х		Х				Τ					1	Х